



Applying Artificial Intelligence on Edge devices using Deep Learning with Embedded optimizations

VLAIO TETRA HBC.2019.2641

User group meeting 2 28-01-2020

[ai-edge.be](https://ai-edge.be)

[iot-incubator.be](https://iot-incubator.be)

[www.eavise.be](https://www.eavise.be)



**KU LEUVEN**

# Agenda

1. Introduction
2. Use cases by the user group
3. Platforms
4. Current work
5. Workshop
6. Networking

# Hype Cycle for Artificial Intelligence, 2020



Gartner

# AI@EDGE in a nutshell

**AI** ->

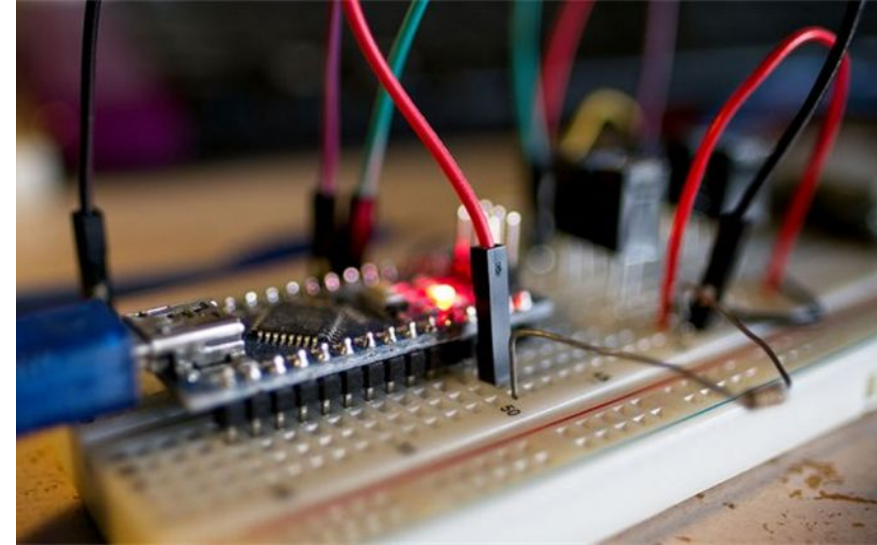
Deep Learning Inference

Trained model -> Target system

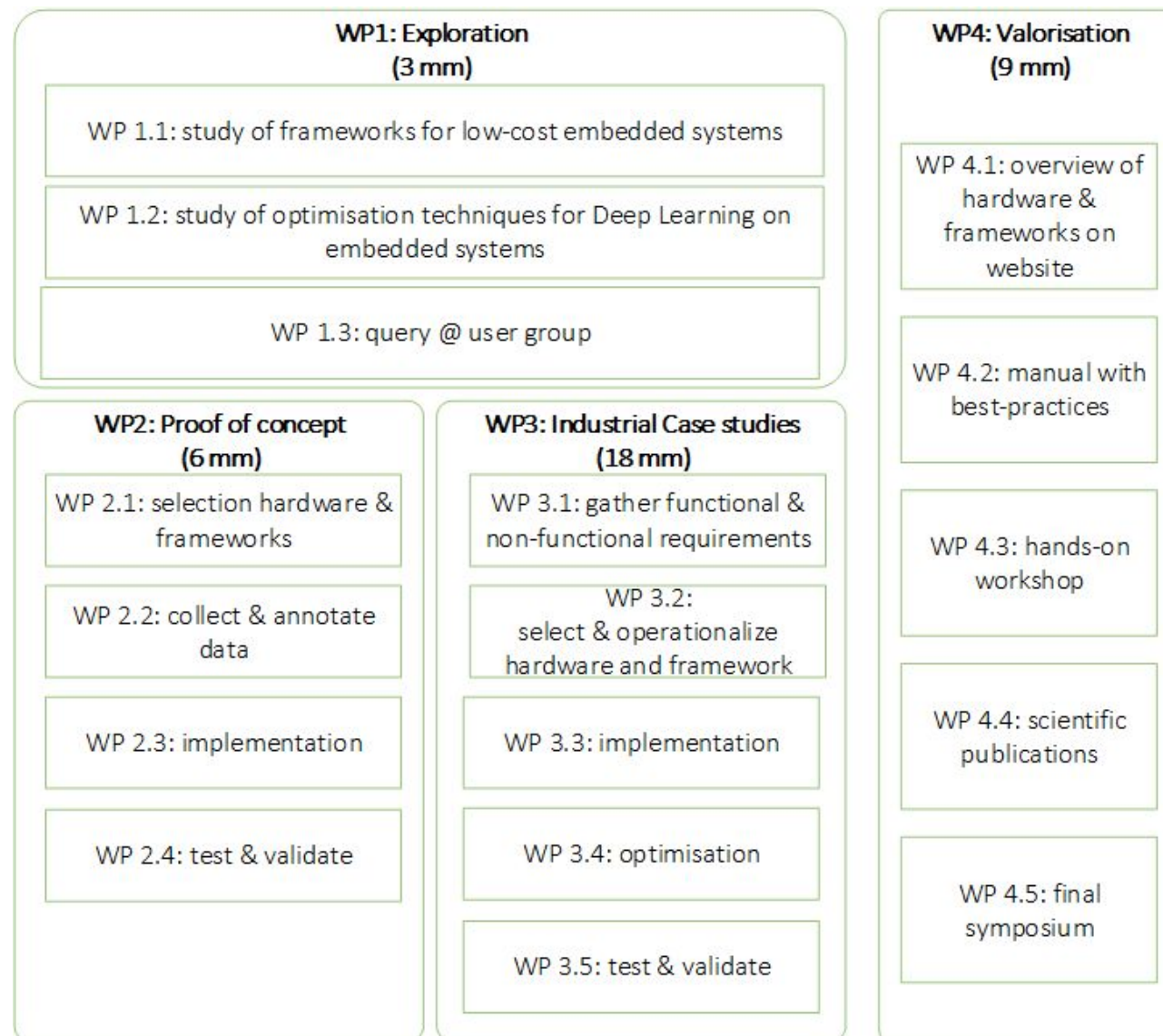
**EDGE** ->

Low-cost small embedded systems

Microcontrollers & System processors



# AI@EDGE overview



# Project planning

- New project member (VIVES): Jonas Lannoo started 01/10/2020
- Project has been extended with 3 months (standard COVID extension) -> end date 31/05/2022
- Milestones have been postponed
  - M1 Proof of concept application: Q2 2021
  - M4 Workshop: Summer 2021
  - M2 Industrial use cases: Q1 2022
  - M3 Manual of best practices: Q1 2022
  - M5 Publications: end of project

# User group use cases

- 1st round of meetings
  - Melexis
  - Digipolis
  - TML
  - Scioteq
  - Picanol
  - E.D.&A.
  - Sensotec
- 2nd round of meetings
  - 6WOLVES
  - Edgise
  - QMineral
  - DP Technics



# Melexis

- Use case: Low resolution thermal image sensor (32x24 pixels)
- Dataset: small dataset recorded by Melexis, semi automatic annotation.
- R-CNN baseline model trained on dataset
- Goal: fit neural network on a microcontroller  $\leq 8\text{€}$
- See: current work



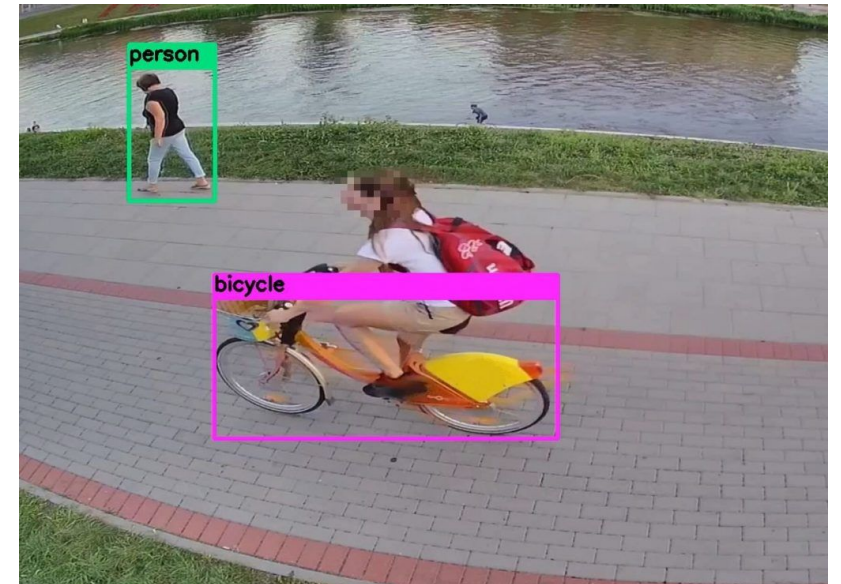
PEOPLE DETECTION WITH  
MLX90640 FIR ARRAY

Melexis  
INSPIRED ENGINEERING



# Digipolis

- Use case: Traffic camera analysis
- Dataset: Privacy issues, standard data sets are not suited, angle of traffic cameras
- Goal: Recognise cyclists, pedestrians, busses



# TML

- Use case: Telraam camera image analysis
- Dataset: Available and annotated
- Goal:
  - Detect pedestrians, (motor)cyclists, cars, heavy vehicles
  - Detect their speed & direction
  - Cost constraint
  - Power constraint



# ScioTeq

- Use case 1: Aircraft 6D pose estimation
- Dataset: un-annotated camera frames + 6D pose
- Goal:
  - Determine plane 6D pose from runway images
- Use case 2: Flight display error detection
- Dataset: un-annotated display frames
- Goal:
  - Detect errors in displayed numbers



# Picanol

- No specific use case
- Use hardware for industrial environment (+50 °C)
- Interests:
  - Measurement and analysis using DL of:
    - Oil temperature
    - Control box environment
    - Humidity
    - Process timings
    - Pressure
    - Wire detection (specific for weaving)
  - Using vision

# E.D.&A.

- Use case: Capacitive touch sensor induction furnace
  - Effectiveness under stress (moisture, dirt, EMI ...)
- Dataset: Available from master thesis
- Goal:
  - Reproduce using NN
  - Better performance
  - STM Devkit
  - $< 8$  ms inference time



# Sensotec

- Use case: Wordprediction & correction in the browser
- Dataset: Available
- Goal:
  - Continuation of master thesis
  - Improving system using NN
  - Generalisable for other languages?
  - Recognition of written letters
  - Target: Chromebook



# Proposal

- Target microcontroller:
  - Case 1: Thermal image sensor
  - Case 2: Capacitive touch
- Target single board computer:
  - Case 3: Traffic Analysis
- Target browser:
  - Case 4: Word prediction
- 2 additional use cases to be determined later in the project



# User group interaction

Questions / remarks?

Other use cases / data sets?

On which non-functional requirements should we focus?  
(Accuracy? Size? Power consumption? Other?)

# Platforms

## Hardware

- STMicroelectronics (STM32)
- Arduino
- Kendryte
- Raspberry Pi (& industrial variants)
- Nvidia Jetson Nano

## Software

- Tensorflow Lite
- Edge impulse
- TFLite on Mbed

# Hardware platforms

STM Development boards with

- Cortex M0+, M3, M4, M7 (32-216MHz)

Arduino Development board

- Nano Sense BLE 33 (Cortex M4, 64MHz, 1MB Flash)

Kendryte K210

- RISC-V Dual Core 64-bit, hardware accelerator

Raspberry Pi 4 SBC

- Quad core Cortex-A72, 1.5GHz, 1-2-4-8GB RAM



# Hardware platforms

## Raspberry Pi 4 Compute module

- Same specs as RPi 4, with industrial support

## Revolution Pi 3+ from KUNBUS

- Industrial variant

## Nvidia Jetson Nano

- Quad-core ARM A57, 1.43GHz,  
4GB RAM + 128 Core GPU



# TensorFlow Lite



## Pick a model

Pick a new model or retrain an existing one.



## Convert

Convert a TensorFlow model into a compressed flat buffer with the TensorFlow Lite Converter.



## Deploy

Take the compressed .tflite file and load it into a mobile or embedded device.



## Optimize

Quantize by converting 32-bit floats to more efficient 8-bit integers or run on GPU.

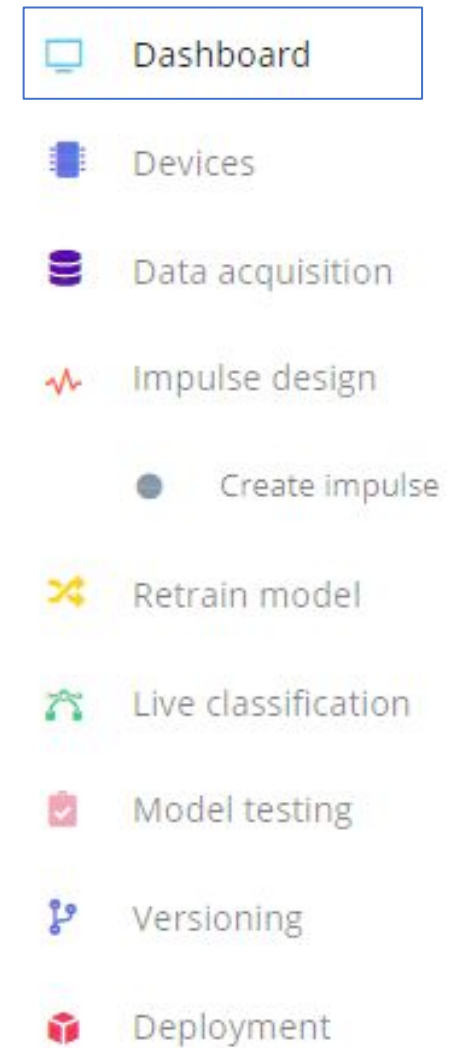
## How it works

## Used in:

- Edge Impulse
- TFLite for Mbed

# Platforms - Edge Impulse

- Online embedded machine learning tool
- TFLite (micro) as backbone
- Project based, versioning and sharing available
- Large community for support
- Extensive documentation available online





# Platforms - Edge Impulse

## Collecting data: Device integration



### Connect a fully supported development board

The best way to get started with real hardware from Nordic, Arduino, OpenMV, ST, Eta Compute and Himax - fully supported by Edge Impulse.



### Use your mobile phone

Use your mobile phone to capture movement, audio or images, and even run your trained model locally. No app required.



### Data from any device with the data forwarder

Capture data from any device or development board over a serial connection, in 10 lines of code.



### Upload data

Already have data? You can upload your existing datasets directly in WAV, JPG, PNG, CBOR or JSON format.



### Integrate with your cloud

The enterprise version of Edge Impulse integrates directly with the data stored in your cloud platform.



Dashboard



Devices



Data acquisition



Impulse design

Create impulse



Retrain model



Live classification



Model testing



Versioning



Deployment




# Platforms - Edge Impulse

- Data acquisition
- Preview data
- Split training/test




DATA COLLECTED

8m 0s













LABELS

2



Collected data

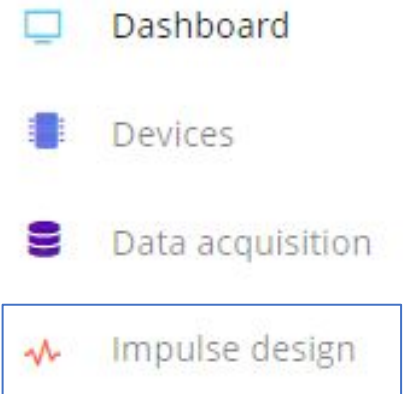


SAMPLE NAME	LABEL	ADDED	LENGTH	
B.json.1nad87as	B	Nov 18 20...	2s	
B.json.1nad81qn	B	Nov 18 20...	2s	
A.json.1nad2g66	A	Nov 18 20...	2s	
A.json.1nad27j4	A	Nov 18 20...	2s	
A.json.1nad20qn	A	Nov 18 20...	2s	
A.json.1nad1rfp	A	Nov 18 20...	2s	

- Dashboard
- Devices
- Data acquisition**
- Impulse design
- Create impulse
- Retrain model
- Live classification
- Model testing
- Versioning
- Deployment

# Platforms - Edge Impulse

## Creating the network (impulse design)



**Time series data**

Axes

accX, accY, accZ

Window size

2000 ms.

Window increase

1 ms.

**Spectral Analysis**

Name

Spectral features

Input axes

☒ accX

☒ accY

☒ accZ

**Neural Network (Keras)**

Name

NN Classifier

Input features

☒ Spectral features

Output features

2 (A, B)

**Output features**

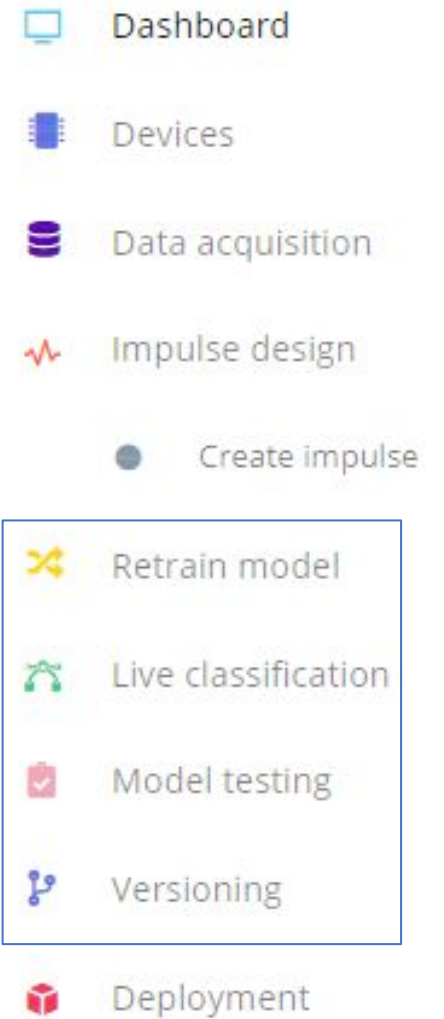
2 (A, B)

Save Impulse

Deployment

# Platforms - Edge Impulse

- Retraining model after changes
- Live classification using your devices (API)
- Check model with test-data
- Store configurations using versioning



# Platforms - Edge Impulse

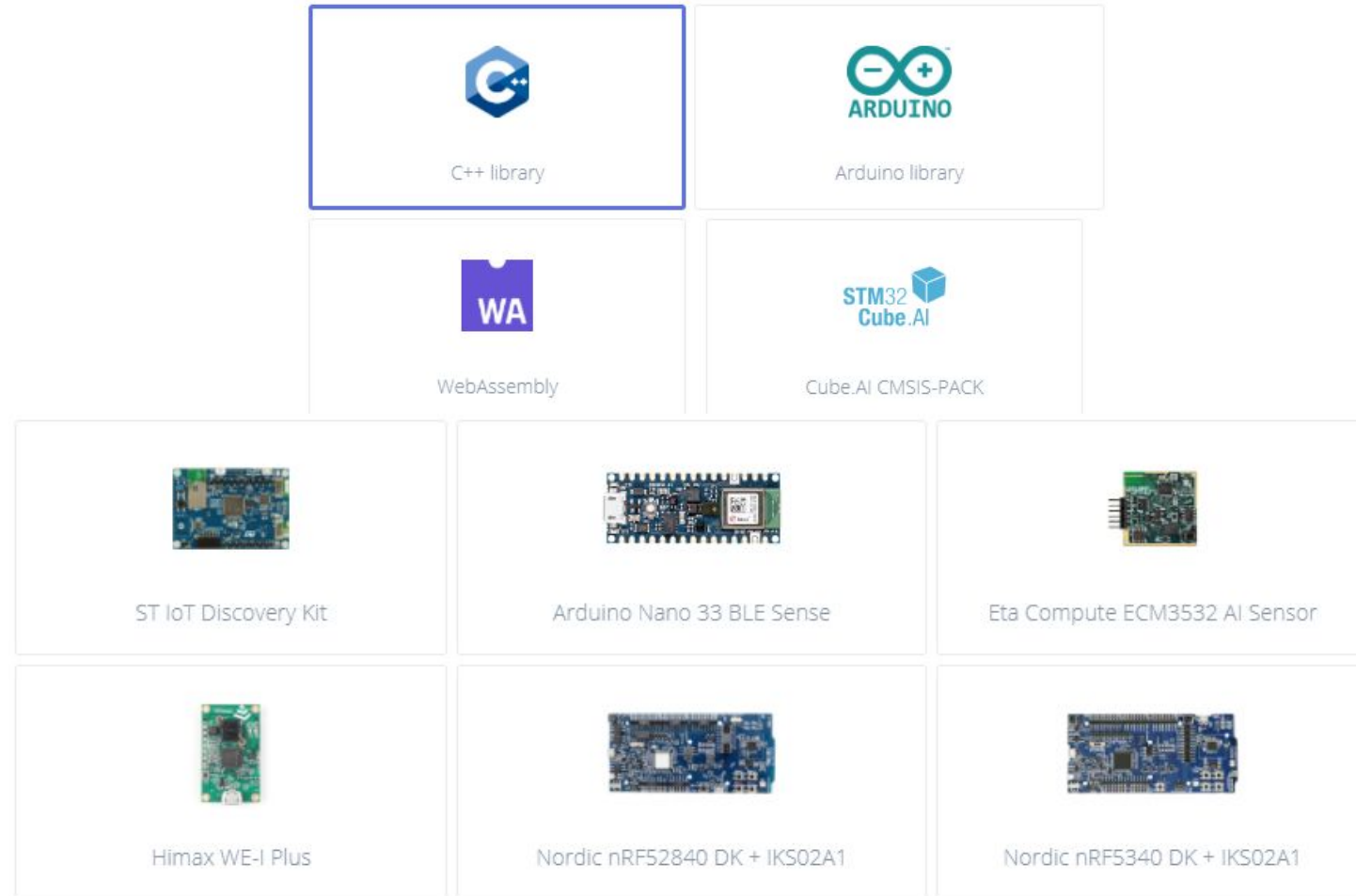


## Deployment

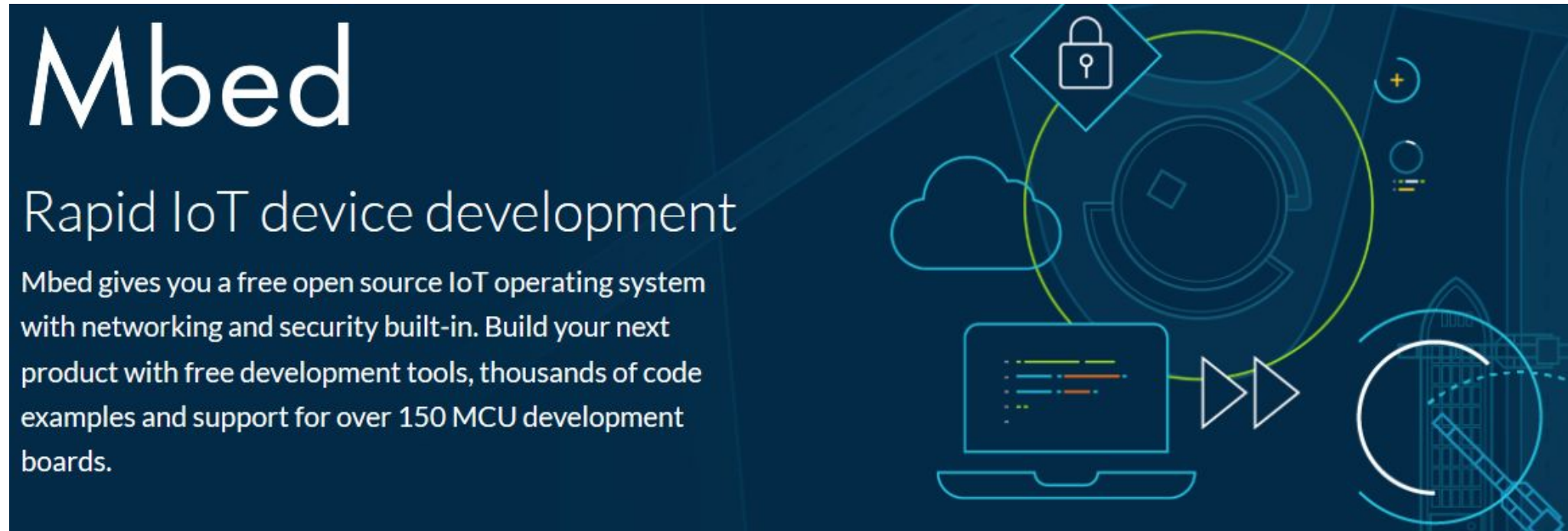
- To library
- As binary for device

## + Optimisation Quantizing model

<b>Quantized (int8)</b> ★ <b>Currently selected</b> <small>This optimization is recommended for best performance.</small>	RAM USAGE	LATENCY
	1.5K	1 ms
<b>Unoptimized (float32)</b> <b>Click to select</b>	ROM USAGE	ACCURACY
	15.3K	16.97%
	RAM USAGE	LATENCY
	1.5K	1 ms
	ROM USAGE	ACCURACY
	17.6K	16.4%



# Mbed platform/ecosystem



**Mbed**

Rapid IoT device development

Mbed gives you a free open source IoT operating system with networking and security built-in. Build your next product with free development tools, thousands of code examples and support for over 150 MCU development boards.

The background features a dark blue gradient with white and light blue line-art icons representing IoT concepts: a cloud, a padlock (security), a gear, a laptop with code, and a circular arrow (cycle/loop).

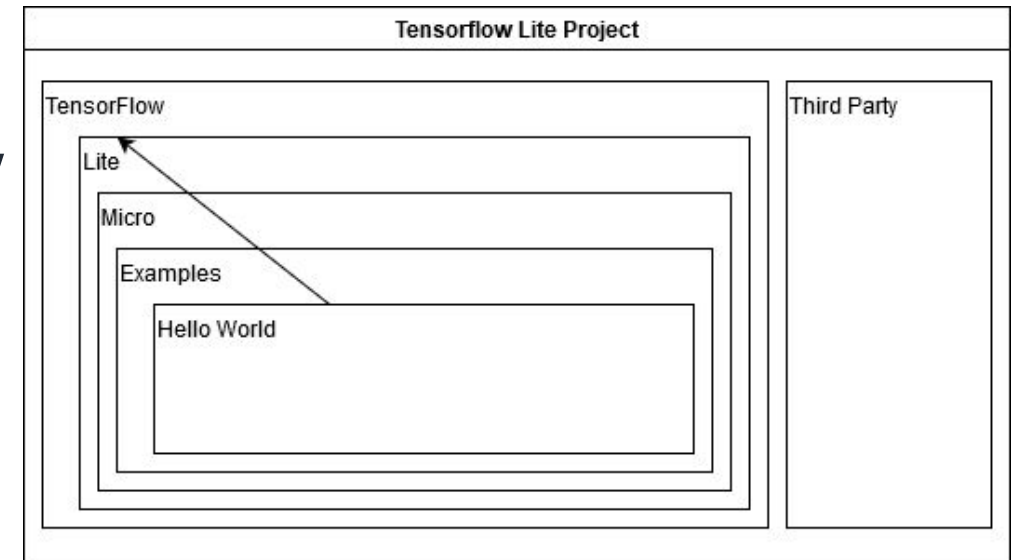
Mbed OS: RTOS or baremetal

Mbed compiler + tools (IDE, CLI,...)

# TensorFlow lite micro for Mbed ecosystem

TensorFlow generator tool using make

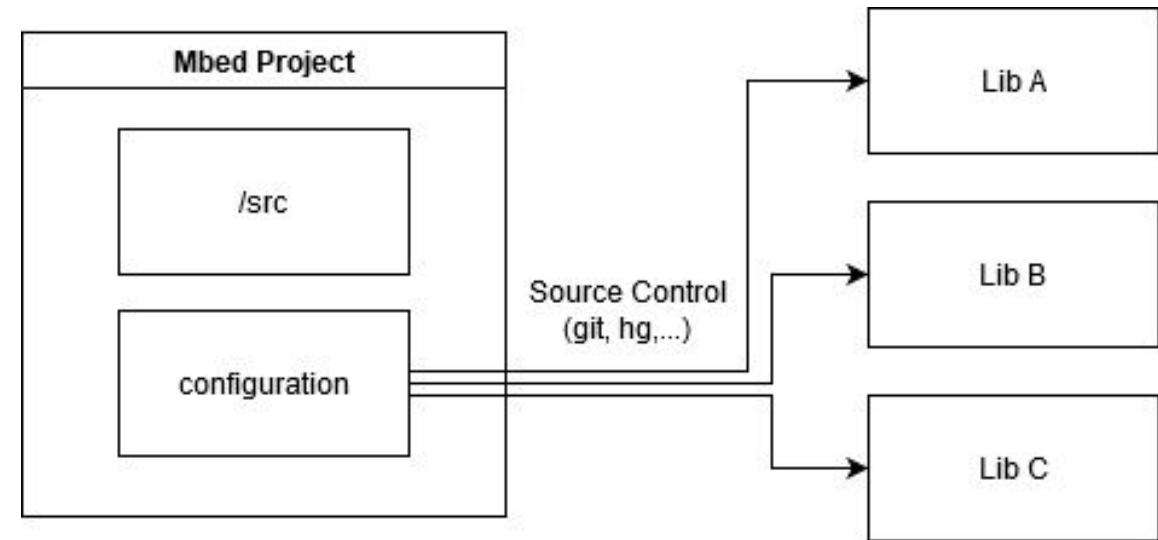
- Inside out project structure
- Applications lives inside the TensorFlow project
- Hard to update or extend
- Hard to implement in existing projects
- Enforces to use Google TensorFlow design style/rules



# TensorFlow lite micro for Mbed ecosystem

Typical Mbed project structure:

- Project source in /src directory
- Dependencies are managed in .lib files
  - Only contain source control origin + explicit version (eg GitHub)
- Lightweight projects
- Easy to update





# TensorFlow lite micro for Mbed ecosystem

TensorFlow Lite Micro as Library (for mbed)

Easy integration (Mbed add command)

Easy updates (Mbed update command)

<https://github.com/sillevl/tensorflow-lite-micro-mbed>

TensorFlow generated project

Excluded application specific files

Fix #include paths

Example: <https://github.com/sillevl/tensorflow-lite-micro-hello-world-mbed>

Hello World application for mbed using TensorFlow Lite as library

# TensorFlow Lite Docker Helper

TensorFlow is developed in the Linux ecosystem

Hard to use in a Windows environment

--> Docker container helper to generate projects

- Docker container containing:
  - TensorFlow project
  - Linux build tools
  - mbed build tools

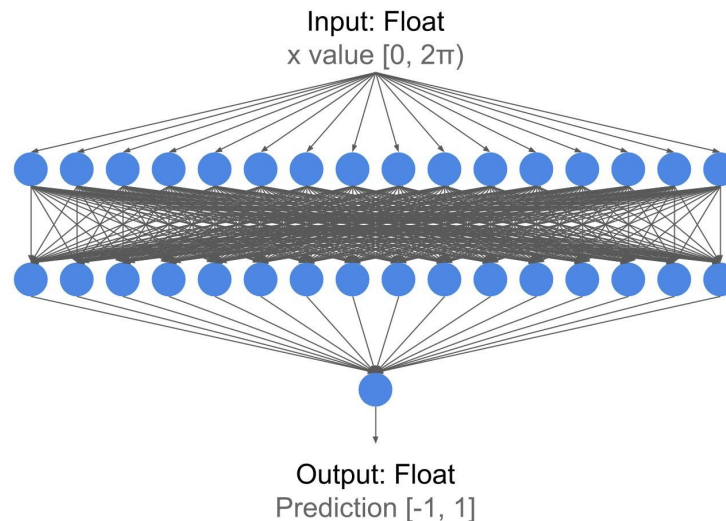
Generate new projects on windows

<https://github.com/sillevl/tensorflow-lite-micro-docker-mbed-helper>

# Benchmark

## Tensorflow Lite Micro Hello World example

- Model that replicates a sine function
- Absolute basics example
- 3-layer, fully connected neural network with a single, floating point input and a single, floating point output



# Benchmark targets

mbd-os (v6.6.0) with mbed-cli  
GCC (v9.3.1)

1000 iterations

- Cortex-M0+
  - STM32L073RZ @ 32MHz
- Cortex-M3
  - LPC1768 @ 96Mhz
- Cortex-M4
  - STM32F446RE @ 180Mhz
  - STM32L476RG, STM32L432KC, STM32L452RE, STM32L4S5VI @ 80 Mhz
  - K64F @ 120Mhz
- Cortex-M7
  - STM32F767ZI @ 216Mhz

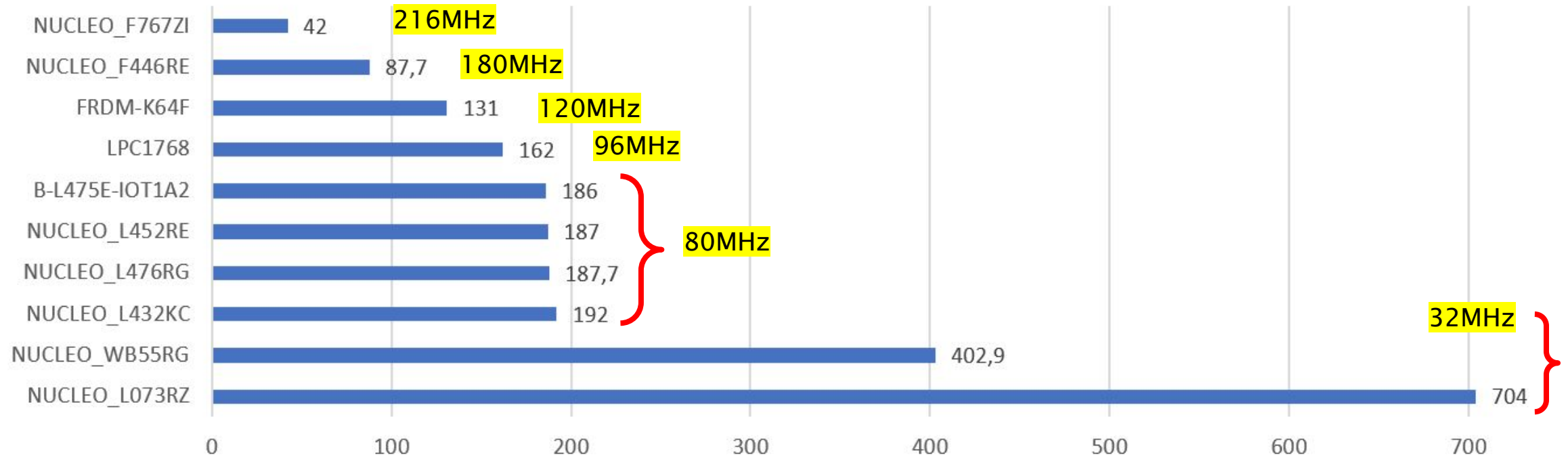


# Benchmark results

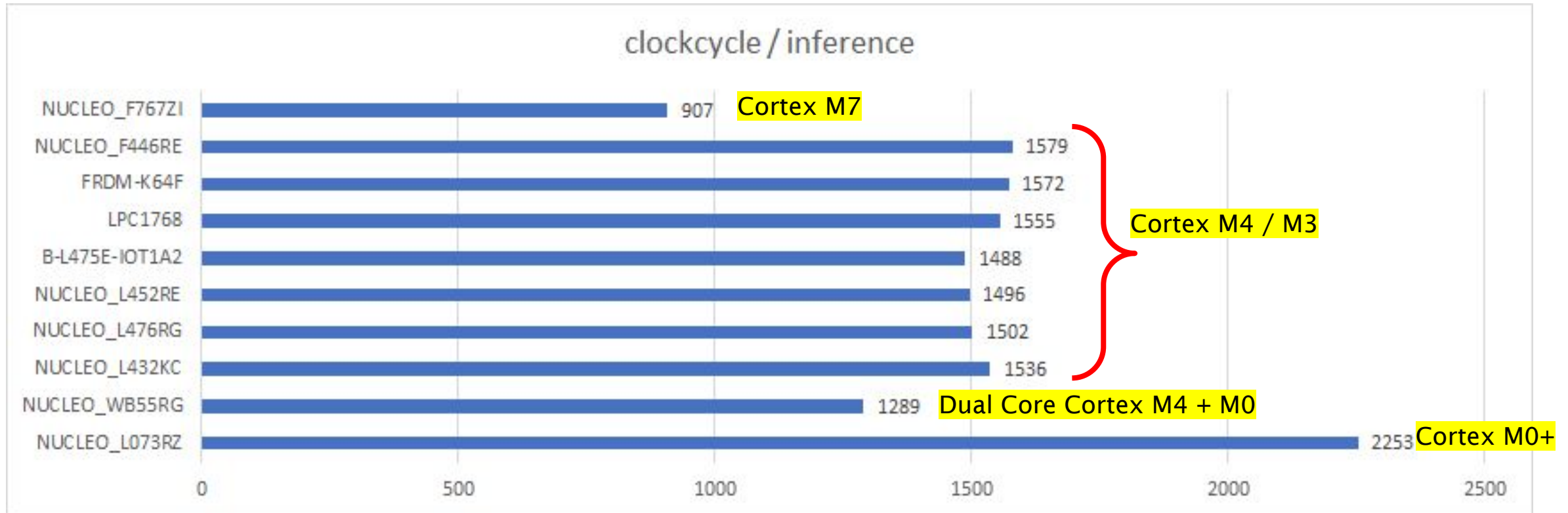
Board	inference time (μs)	Manufacturer	CPU	Family	CPU clock (MHz)	inference frequency (Hz)	inference frequency per Mhz CPU clock	clock cycles per inference
NUCLEO_L073RZ	704	ST	STM32L073RZ	M0+	32	1420	44,4	2253
NUCLEO_WB55RG	402,9	ST	STM32WB55RG	M4	32	2482	77,6	1289
NUCLEO_L432KC	192	ST	STM32L432KC	M4	80	5208	65,1	1536
NUCLEO_L476RG	187,7	ST	STM32L476RG	M4	80	5328	66,6	1502
NUCLEO_L452RE	187	ST	STM32L452RE	M4	80	5348	66,8	1496
B-L475E-IOT1A2	186	ST	STM32L4S5VI	M4	80	5376	67,2	1488
LPC1768	162	NXP	LPC1768	M3	96	6173	64,3	1555
FRDM-K64F	131	NXP	MK64F	M4	120	7634	63,6	1572
NUCLEO_F446RE	87,7	ST	STM32F446RE	M4	180	11403	63,3	1579
NUCLEO_F767ZI	42	ST	STM32F767ZI	M7	216	23810	110,2	907

# Benchmark inference time

inference time ( $\mu$ s)



# Benchmark cpu speed





# Benchmark conclusions

- Exact same codebase (model, implementation, compiler, toolchain)
- Inference time scales inversely proportional with CPU clock speed
- ARM family has a significant impact on inference time

# User group interaction

Questions / remarks?

Which platforms (hardware / software) are relevant for you?

Do you need more detailed information on the benchmark?

Hardware accelerators (e.g. Kendryte) and FPGA's are out of scope of this project. Would it be interesting to take these platforms in consideration?

# Current work

- Industrial use cases
  - Thermal Image Sensor
  - Traffic Analysis
- Proof of concept use cases
  - Seat detection
  - A/B writing
- Workshop

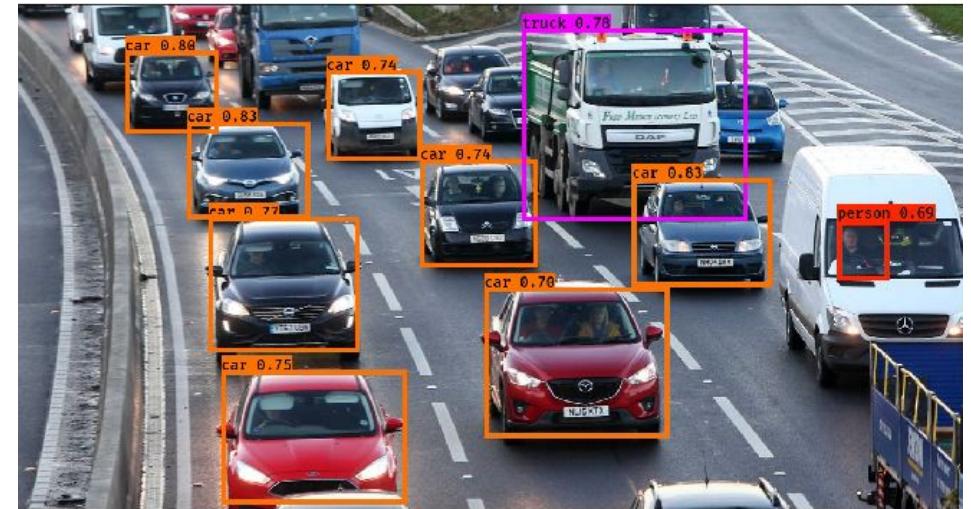
# Melexis use case

Thermal Image sensor

# Object Detection on Raspberry Pi

Many object detectors already exist:  
YOLO (TinyYOLO), SSD (MobileNet backbone),...  
But... very slow on CPU-only device

TensorFlow Lite to the rescue!  
Ideal for “small” devices



# Results on Raspberry Pi

Many models available online:

- SSD + MobileNetv1
- Quantized and trained on MS COCO

Results on Raspberry Pi :

RPI 3B+ (1GB RAM) 0:38s per frame

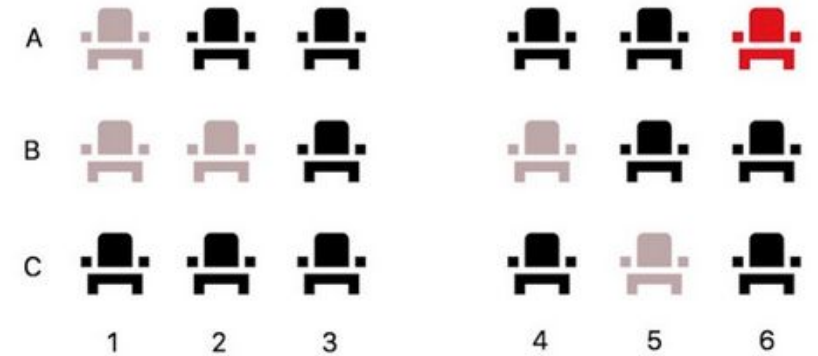
RPI 4 (4GB RAM) 0:19s per frame

↔ multiple seconds without TF Lite



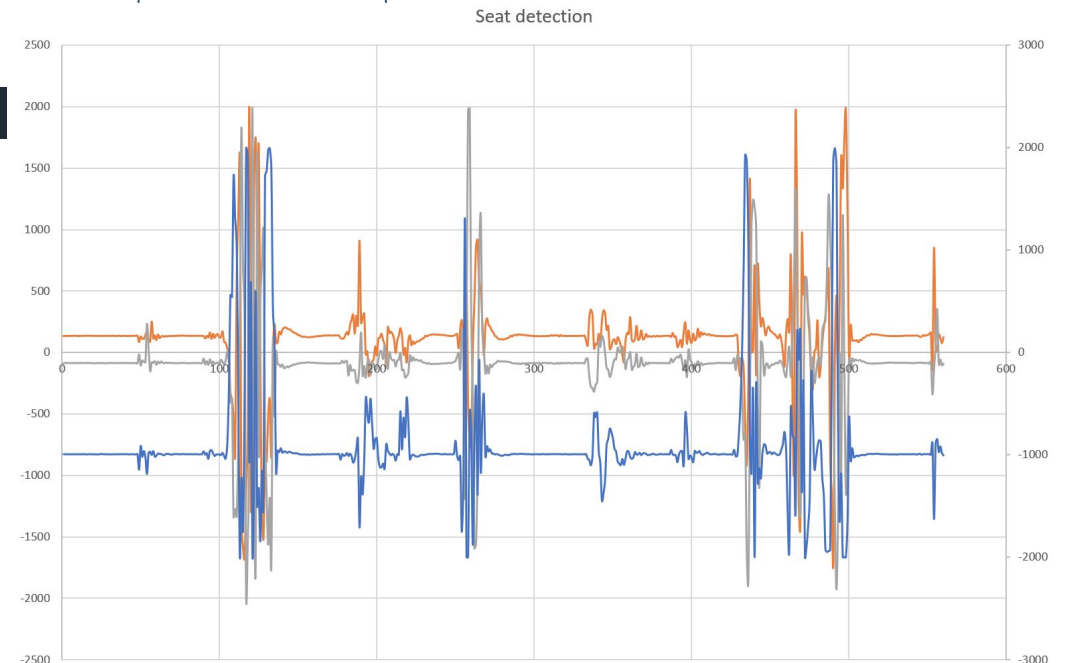
# Seat detection case

- Seat detection
- Count number of people in a room
- Prevent false positive (eg, cleaning personnel will move all seats)
- Large inference from nearby movements
- Accelerometer, gyroscope, magnetometer?



seat occupied

nearby seat occupied



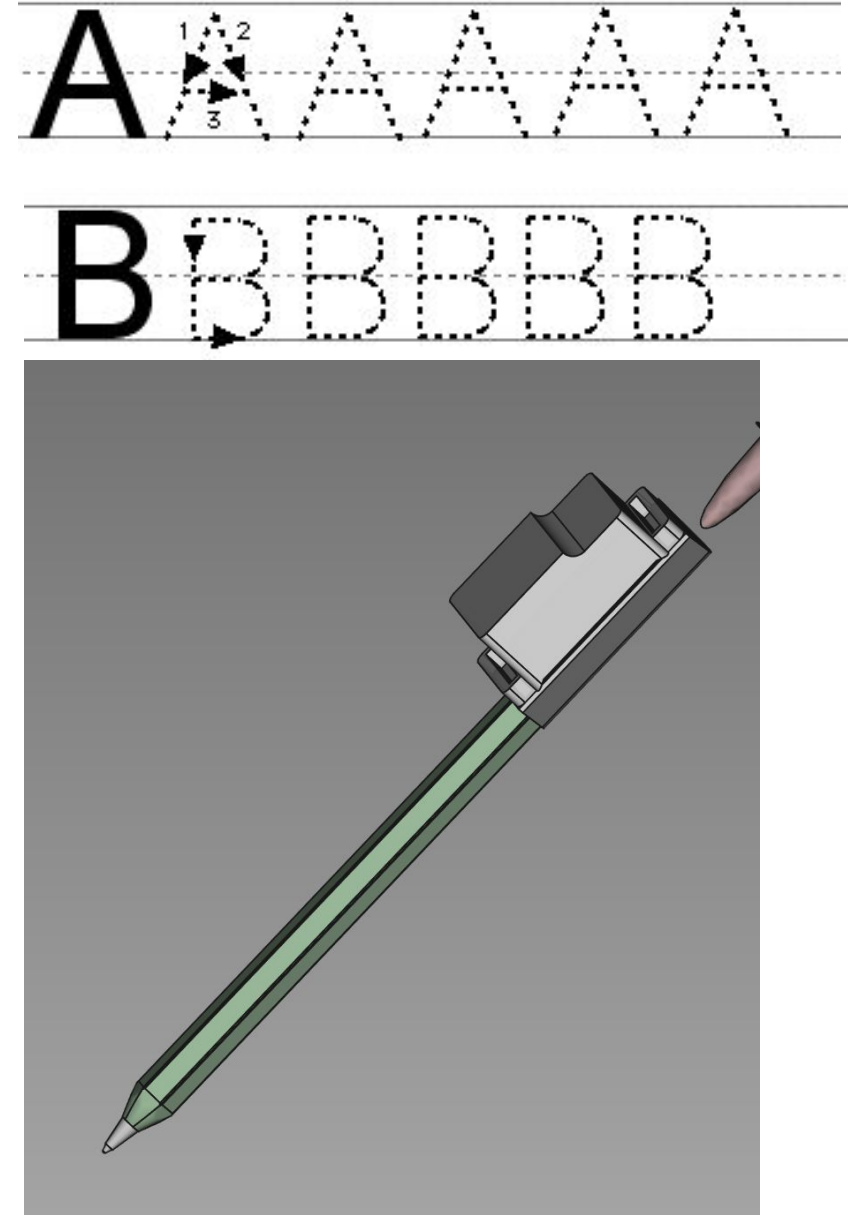


# Workshop - “ABWriting”

Written letter recognition  
ST Sensortile mounted on a pen  
Using accelerometer data

- Collecting data
- Training NN
- Inference on the device

Wireless communication using BLE



# ST SensorTile development kit

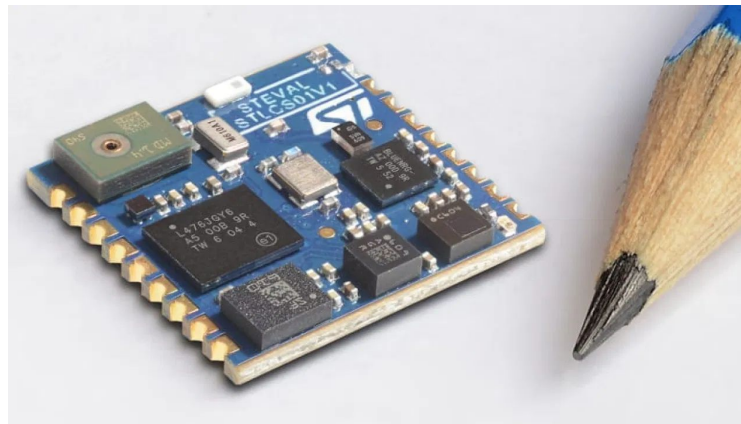
STM32L476JG microcontroller - Cortex M4

80MHz - 1MB Flash - 128KB SRAM

Bluetooth Low Energy

Sensors:

- Accelerometer
- Gyroscope
- Magnetometer
- Mems Microphone
- SD-Card
- Temperature
- Pressure



# tinyML Summit 2021

*Enabling ultra-low Power Machine Learning at the Edge*

**March 22-26, 2021 | Online**

Tutorials about

- Magic Wand learning
- Image sensor & low-power
- Quantising, pruning with AIMET
- Industrial grade applications with Edge Impulse

Several keynotes, tinyTalks & breakout sessions

Free! Registration required.

<https://www.tinyml.org/summit2021/>

# Administration

- Rules of procedure (reglement van orde)
- User Poll
- Next user group meeting: June 2021

# Networking: <https://spatial.chat/s/eavise>

## Access Procedure

- **Click** on the following link: <https://spatial.chat/s/eavise>
- Fill in your name in the *Full Name* box and your company in the *About* box
- Allow the browser to use your microphone and camera
- Check your audiovisual settings and click on *Join Space*

## Getting around in the space

- **Drag** your avatar around to freely move through the space. If you are **close enough** to other people, you **can talk** to each other
- The space is split up in **two rooms**. You can **click on a name** of a **room** in the lefthand list to jump to that room.
- **Click on a name of another visitor** at the lefthand list to move quickly towards him or her and start a conversation.

